

# Non-classical elastic behavior: A continuum mechanics perspective

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Funded by the  
European Union

## Galway, Ireland

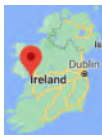
Marie Skłodowska-Curie Postdoctoral Fellowship (2021-2023)

Traumatic  
brain injury



NUI Galway

- Galway: 80 000 hab
- NUIG: 18 000 students, 2 700 staff
- Maths: 30 academics



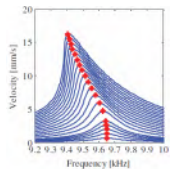
[www.esmc2022.org](http://www.esmc2022.org)



## Marseille, France

PhD (2015-2018)

Nonlinear  
acoustics

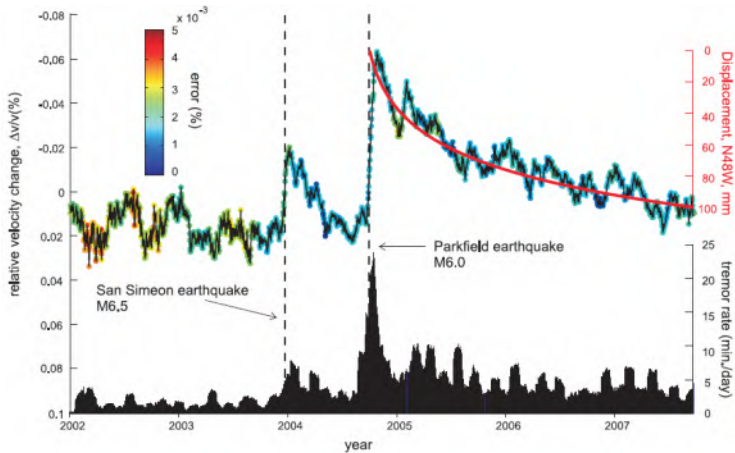


Subject

Modelling the softening behaviour of geomaterials


- ① Softening behaviour of geomaterials
- ② Traumatic brain injury

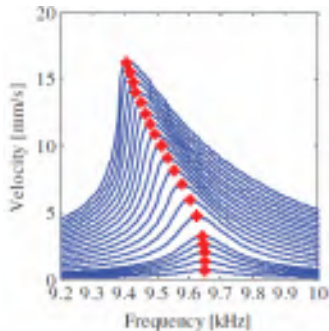
# Seismology



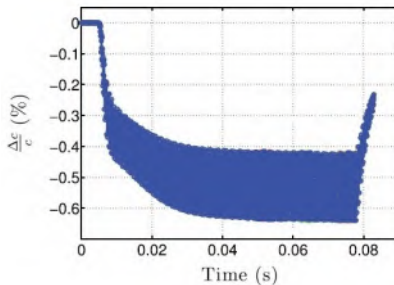
 Brenghier et al. 2008

## Experimental overview

Vibrating sandstone bar  *TenCate et al. 2019*




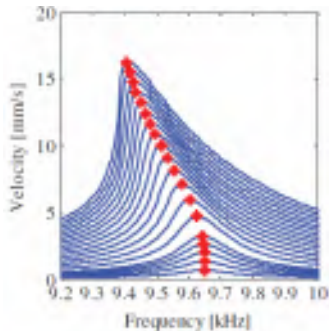
Resonance



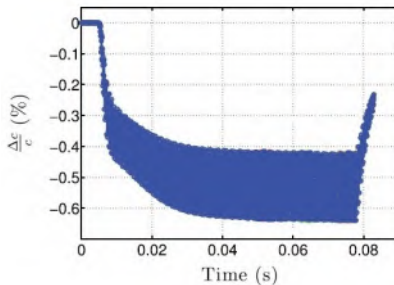
Dynamic Acoustoelasticity (DAE)

## Experimental overview

Vibrating sandstone bar  *TenCate et al. 2019*



Resonance



Dynamic Acoustoelasticity (DAE)



## Modelling literature

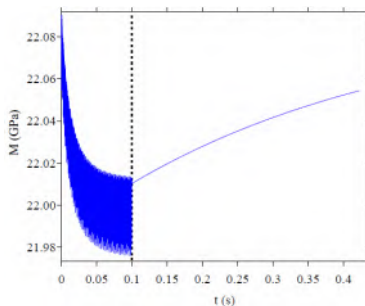
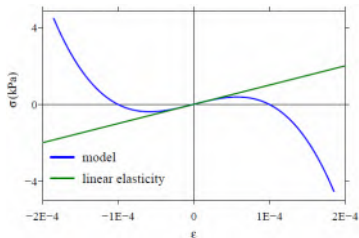
Nonlinear elasticity + viscosity

$$\sigma = E \underbrace{(\varepsilon + \dots)}_{\sigma^e(\varepsilon)} + \eta \dot{\varepsilon}$$

Soft-ratchet model  *Vakhnenko et al. 2004*

$$\sigma = (1 - g) \sigma^e(\varepsilon) + \eta \dot{\varepsilon}$$

$$\dot{g} = \omega_r (g_{\text{eq}}(\sigma) - g)$$

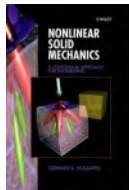
Simulation  *Favrie et al. 2015*

## Solid mechanics

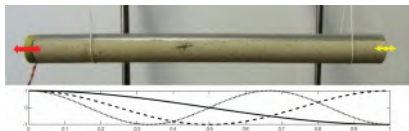
### Damage mechanics

### Nonlinear viscoelasticity

- nonlinear behaviour
- transients, dissipation
- reversible, repeatable



### Continuum assumption



# Classical mechanics

Kinematics · Balance laws · Thermodynamics

## Clausius–Duhem inequality

$$\mathcal{D} = \left( \sigma - \frac{\partial U}{\partial \varepsilon} \right) \dot{\varepsilon} - \frac{\partial U}{\partial \mathbf{g}} \dot{\mathbf{g}} \geq 0$$

Nonlinear elasticity + viscosity

✓ consistent:  $\mathcal{D} = \eta \dot{\varepsilon}^2 \geq 0$

$$\sigma = \overbrace{\sigma^e(\varepsilon)}^{\partial U / \partial \varepsilon} + \eta \dot{\varepsilon}$$

Soft-ratchet model

✗ not checked initially

✗ not satisfied 📖 *Berjamin et al. 2017*

$$\sigma = \overbrace{(1 - \mathbf{g}) \sigma^e(\varepsilon)}^{\partial U / \partial \varepsilon} + \eta \dot{\varepsilon}$$

$$\dot{\mathbf{g}} = \omega_r (\mathbf{g}_{\text{eq}}(\sigma) - \mathbf{g})$$

## Internal-variable model

Keep the stress  *Berjamin et al. 2017*

$$\sigma = \overbrace{(1 - g) \sigma^e(\varepsilon)}^{\partial U / \partial \varepsilon} + \eta \dot{\varepsilon} \quad \Longrightarrow \quad U = (1 - g) W^e(\varepsilon) + \phi(g)$$

Thermodynamics:  $-\frac{\partial U}{\partial g} \dot{g} \geq 0$

Relaxation parameter  $\Omega_r > 0$

$$\dot{g} = -\Omega_r \frac{\partial U}{\partial g}, \quad \text{i.e.} \quad \boxed{\dot{g} = \Omega_r (W^e(\varepsilon) - \phi'(g))}$$

## Finite volume implementation

Balance laws for  $\mathbf{q} = (\varepsilon, v, \mathbf{g})^\top$

$$\partial_t \mathbf{q} + \partial_x \mathbf{f}(\mathbf{q}) = \mathbf{r}(\mathbf{q}) + \mathbf{D} \partial_{xx} \mathbf{q}$$

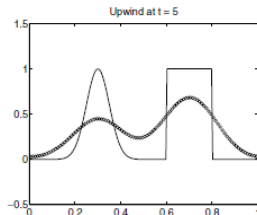
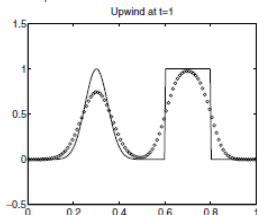
Scheme

$$\mathbf{q}_i^* = \mathbf{q}_i^n + \Delta t (\mathbf{r}(\mathbf{q}_i^n) + \mathbf{D} \delta_{xx} \mathbf{q}_i^n)$$

$$\mathbf{q}_i^{n+1} = \mathbf{q}_i^* - \frac{\Delta t}{\Delta x} (\mathbf{f}_{i+1/2}^* - \mathbf{f}_{i-1/2}^*)$$

Why finite volumes?  LeVeque 2002

$$q_t + q_x = 0$$



## Finite volume implementation


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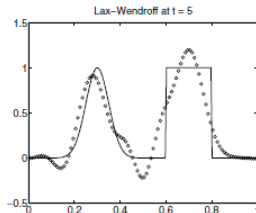
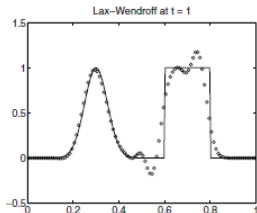
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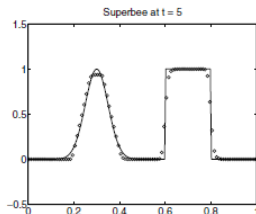
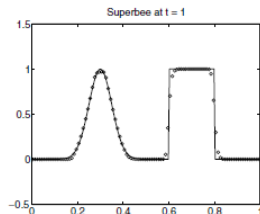
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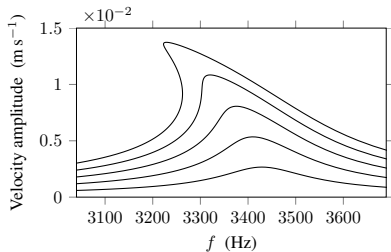
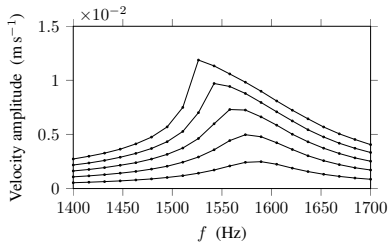
Why finite volumes?  LeVeque 2002

$$q_t + q_x = 0$$



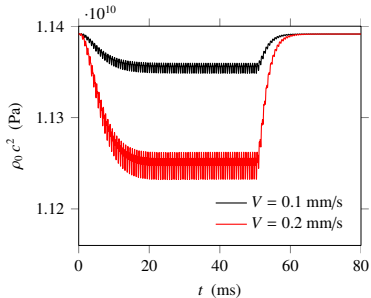
## Results

### Resonance Benjamin et al. 2018



### DAE

- ✓ qualitative agreement
- ✓ parametric studies

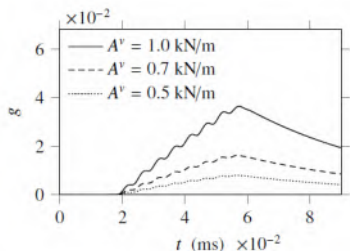
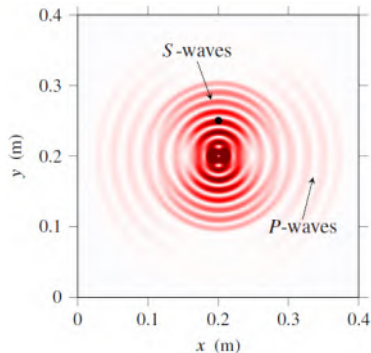




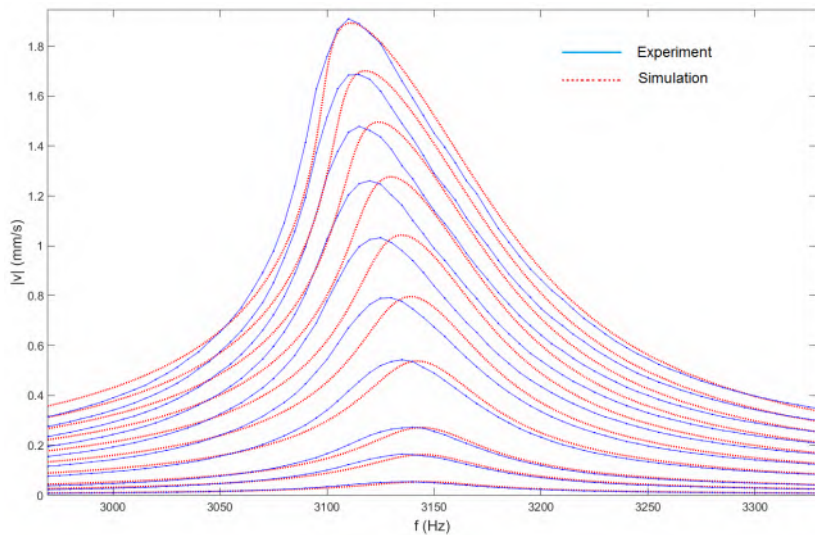
## Multiple space dimensions

2D-3D  Benjamin et al. 2019

$$\begin{aligned} \sigma &= (1 - g) \sigma^e(\varepsilon) + \eta \dot{\varepsilon} \\ \dot{g} &= \Omega_r (W^e(\varepsilon) - \phi'(g)) \end{aligned} \quad \Rightarrow \quad \begin{aligned} \mathbf{S} &= (1 - g) \mathbf{S}^e(\mathbf{E}) + \zeta(\text{tr} \dot{\mathbf{E}}) \mathbf{I} + \eta \dot{\mathbf{E}} \\ \dot{g} &= \Omega_r (W^e(\mathbf{E}) - \phi'(g)) \end{aligned}$$



## Quantitative agreement?



## Conclusion

Change of material properties?

Micromechanics: Damage? Hydraulics? Friction?

Sensitivity with laboratory conditions

Complex rheological behaviour



- ① Softening behaviour of geomaterials
- ② Traumatic brain injury

# Biomechanics

## Mechanical waves

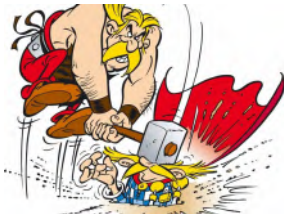
- imaging, testing
- nonlinear (visco)-elasticity

## Soft tissues

- nearly incompressible ( $\kappa \simeq 10^3 \mu$ )
- multiphasic



## Traumatic brain injury

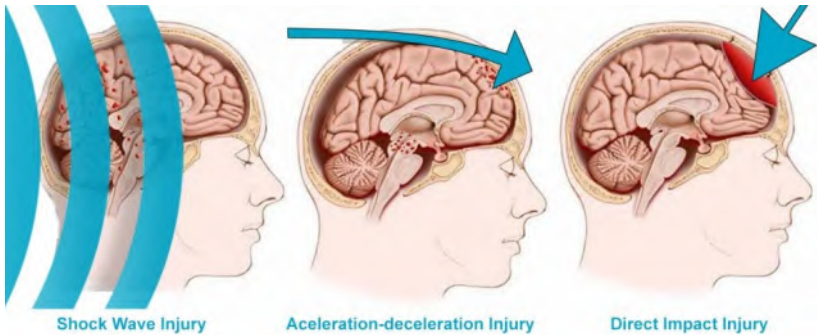


Primary injury: motion

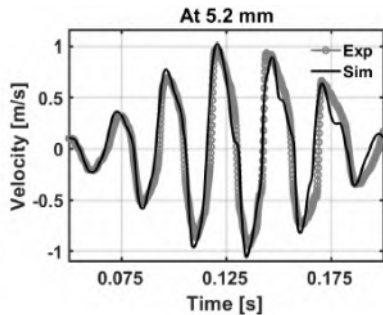
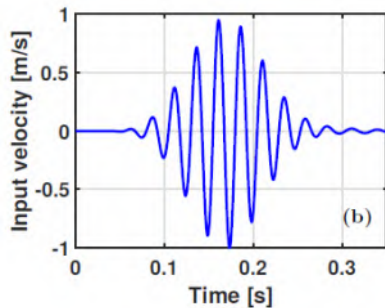


Secondary injury: swelling

## Primary injury




## Shock wave formation



 Chandrasekaran et al. 2021



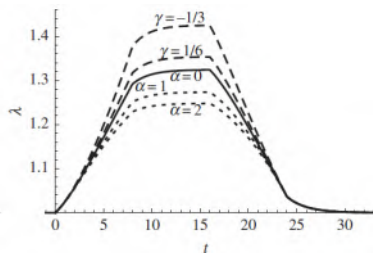
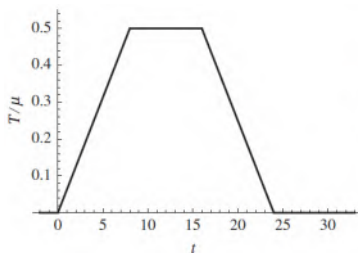
## Soft viscoelastic tissue

Quasi-linear viscoelasticity  *De Pascalis et al. 2014*

$$\mathbf{S} = -p\mathbf{C}^{-1} + \mathcal{G} * \dot{\mathbf{S}}^e$$

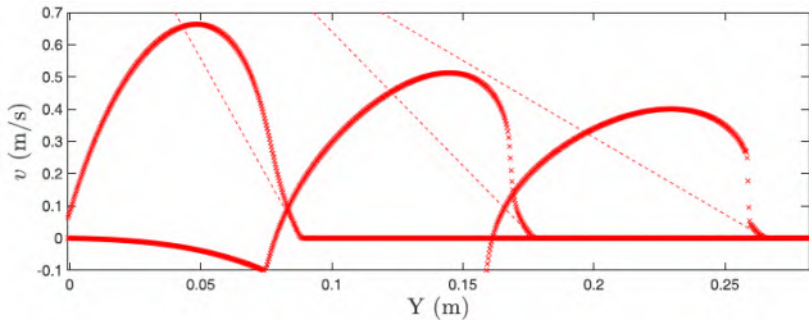
Prony series

$$\mathcal{G}(t) = [1 - g(1 - e^{-\omega_r t})] H(t)$$



## Direct impact simulation

Shock formation distance  Benjamin et al. 2022



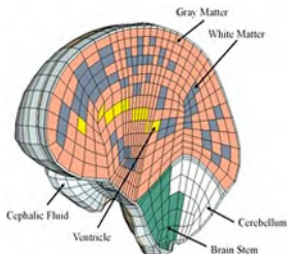
$\times$  approx. estimations fail

## Available soon

Poroelastic behaviour

Swelling model

3D code



## Acknowledgements

- B. Lombard, N. Favrie, G. Chiavassa, C. Payan, E. Sarrouy (Marseille), M. Rémillieux (Los Alamos), S. Junca (Nice)
- M. Destrade, B. Tripathi, V. Balbi (NUI Galway), S. Chockalingam (MIT)

Thank you for your attention!

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