Simulation of Translational and Rotational ground motions

A Short Presentation

Presented by Anjali Dhabu

Post-doctoral Research Associate Institute of Geophysics University of Hamburg, Germany

May 27, 2022

- The characteristics of seismic waves depend on:
	- **4 Earthquake source**
	- ² Medium of wave propagation
	- ³ Boundary conditions

- The characteristics of seismic waves depend on:
	- **4** Earthquake source
	- ² Medium of wave propagation
	- **3** Boundary conditions
- My work addresses the modelling aspect of all these three factors.

- The characteristics of seismic waves depend on:
	- **4** Earthquake source
	- ² Medium of wave propagation
	- **3** Boundary conditions
- My work addresses the modelling aspect of all these three factors.
- **Earthquake source**

- The characteristics of seismic waves depend on:
	- **4** Earthquake source
	- ² Medium of wave propagation
	- **3** Boundary conditions
- My work addresses the modelling aspect of all these three factors.
- **Earthquake source**
	- ▶ Seismic sources are represented as rectangular regions with slip distributed over the surface of the fault plane

Tohoku (2011) source model

- The characteristics of seismic waves depend on:
	- **4** Earthquake source
	- ² Medium of wave propagation
	- **3** Boundary conditions
- My work addresses the modelling aspect of all these three factors.

Earthquake source

- ▶ Seismic sources are represented as rectangular regions with slip distributed over the surface of the fault plane
- ▶ Extreme slips are observed near the hypocenter and are responsible for the peak amplitude observed in simulated ground motions

Asperities in literature (Mai et al.,(2005))

The Seismic Source Regions of SMG in rupture model

• Effective Dimensions

▶ Effective slip dimensions are defined such that, each sub-fault of the effective slip contributes to 90% of total cumulative energy

The Seismic Source ² Regions of SMG in rupture model

• Effective Dimensions

▶ Effective slip dimensions are defined such that, each sub-fault of the effective slip contributes to 90% of total cumulative energy

- **Regions of Strong Motion Generation**
	- \triangleright Q-Q plot shows that higher values of slip tend to deviate from standard exponential distribution.

Q-Q plot for 1991 Sierra Madre earthquake

The Seismic Source 2008 and 2008 Regions of SMG in rupture model

• Effective Dimensions

▶ Effective slip dimensions are defined such that, each sub-fault of the effective slip contributes to 90% of total cumulative energy

- **Regions of Strong Motion Generation**
	- \triangleright Q-Q plot shows that higher values of slip tend to deviate from standard exponential distribution.

The Seismic Source ² Regions of SMG in rupture model

• Effective Dimensions

▶ Effective slip dimensions are defined such that, each sub-fault of the effective slip contributes to 90% of

- total cumulative energy **and Strong Motion Generation**
	- \triangleright Q-Q plot shows that higher values of slip tend to deviate from standard exponential distribution.
	- ▶ Finally, we get the regions of SMG

For a given rupture model, effective dimensions and regions of SMG are calculated

- For a given rupture model, effective dimensions and regions of SMG are calculated
- A total of 159 rupture models are analyzed

- For a given rupture model, effective dimensions and regions of SMG are calculated
- A total of 159 rupture models are analyzed
- Regression analysis is carried out to \bullet estimate rupture parameters viz.

- For a given rupture model, effective dimensions and regions of SMG are calculated
- A total of 159 rupture models are analyzed
- Regression analysis is carried out to \bullet estimate rupture parameters viz.
	- **4** Effective length
	- Effective width
	- **3** Effective area
	- **4** Mean effective slip

- For a given rupture model, effective dimensions and regions of SMG are calculated
- A total of 159 rupture models are analyzed
- Regression analysis is carried out to \bullet estimate rupture parameters viz.
	- **4** Effective length
	- **2** Effective width
	- **Effective area**
	- **4** Mean effective slip
	- **5** Threshold slip
	- **6** Area of SMG

- For a given rupture model, effective dimensions and regions of SMG are calculated
- A total of 159 rupture models are analyzed
- Regression analysis is carried out to estimate rupture parameters viz.
	- **4** Effective length
	- **2** Effective width
	- **3** Effective area
	- **4** Mean effective slip
	- **5** Threshold slip
	- **6** Area of SMG
- These equations can be used to predict the rupture parameters for future earthquake
- DOI: 10.1007/s00024-019-02136-0 \bullet

Medium of Wave Propagation Homogeneous Reduced Micropolar half-space

• The equations of motion for reduced micropolar half space (RMP) are:

$$
c_1^2 \nabla \nabla \bullet \vec{u} - c_2^2 \nabla \times \nabla \times \vec{u} + \frac{j w_0^2}{2} \nabla \times \vec{\Theta} - \vec{\tilde{u}} = 0
$$

$$
\frac{w_0^2}{2}\nabla \times \vec{u} + w_0^2 \vec{\Theta} - \vec{\tilde{\Theta}} = 0
$$

$$
c_1^2 = \frac{\lambda + \mu + \kappa}{\rho}, c_2^2 = \frac{\mu + \kappa}{\rho}, w_0^2 = \frac{2\kappa}{\rho j}
$$

- \blacktriangleright λ is Lame's constant
- \blacktriangleright μ is Eringen's shear modulus
- ▶ *κ* describes the microstructure of the medium
- \blacktriangleright *j* is the rotational inertia of the medium

Medium of Wave Propagation Homogeneous Reduced Micropolar half-space

• The equations of motion for reduced micropolar half space (RMP) are:

$$
c_1^2 \nabla \nabla \bullet \vec{u} - c_2^2 \nabla \times \nabla \times \vec{u} + \frac{j w_0^2}{2} \nabla \times \vec{\Theta} - \vec{\tilde{u}} = 0
$$

$$
\frac{w_0^2}{2}\nabla \times \vec{u} + w_0^2 \vec{\Theta} - \vec{\tilde{\Theta}} = 0
$$

$$
c_1^2 = \frac{\lambda + \mu + \kappa}{\rho}, c_2^2 = \frac{\mu + \kappa}{\rho}, w_0^2 = \frac{2\kappa}{\rho j}
$$

- \blacktriangleright λ is Lame's constant
- \blacktriangleright μ is Eringen's shear modulus
- ▶ *κ* describes the microstructure of the medium
- \blacktriangleright *j* is the rotational inertia of the medium

Elastic half-space

$$
c_1^2 \nabla \nabla \bullet \vec{u} - c_2^2 \nabla \times \nabla \times \vec{u} - \vec{u} = 0
$$

$$
c_1^2 = \frac{\lambda + \mu}{\rho}, c_2^2 = \frac{\mu}{\rho}
$$

Medium of Wave Propagation Homogeneous Reduced Micropolar half-space

• The equations of motion for reduced micropolar half space (RMP) are:

$$
c_1^2 \nabla \nabla \bullet \vec{u} - c_2^2 \nabla \times \nabla \times \vec{u} + \frac{j w_0^2}{2} \nabla \times \vec{\Theta} - \vec{u} = 0
$$

$$
\frac{w_0^2}{2}\nabla \times \vec{u} + w_0^2 \vec{\Theta} - \vec{\tilde{\Theta}} = 0
$$

$$
c_1^2 = \frac{\lambda + \mu + \kappa}{\rho}, c_2^2 = \frac{\mu + \kappa}{\rho}, w_0^2 = \frac{2\kappa}{\rho j}
$$

- \blacktriangleright λ is Lame's constant
- \blacktriangleright μ is Eringen's shear modulus
- ▶ *κ* describes the microstructure of the medium
- \blacktriangleright *j* is the rotational inertia of the medium

Elastic half-space

$$
c_1^2 \nabla \nabla \bullet \vec{u} - c_2^2 \nabla \times \nabla \times \vec{u} - \vec{u} = 0
$$

$$
c_1^2 = \frac{\lambda + \mu}{\rho}, c_2^2 = \frac{\mu}{\rho}
$$

Medium of Wave Propagation 5 and 5 a Homogeneous Reduced Micropolar half-space

Pure and Applied Geophysics. DOI:10.1007/s00024-019-02225-0

10.1007/s10950-021-09983-2

Medium of wave propagation and the control of the state of the sta Layered Reduced Micropolar half-space

Now, the Earth medium is modelled as layered RMP half-space subjected to earthquake forces.

Medium of wave propagation and the control of the state of the state \blacksquare Layered Reduced Micropolar half-space

- Now, the Earth medium is modelled as layered RMP half-space subjected to earthquake forces.
- The methodology is first validated with the simulations for a classical elastic medium.

Medium of Wave Propagation 7 Australian 1999 and 1999 an Layered Reduced Micropolar half-space

For 6M^w 2012 Wutai, Taiwan earthquake with focal depth of 26*.*3km and radial distance 161km

Medium of Wave Propagation 7 and 2012 1999 Medium of Wave Propagation Layered Reduced Micropolar half-space

For 6M^w 2012 Wutai, Taiwan earthquake with focal depth of 26*.*3km and radial distance 161km

- The simulated peak rotation about vertical axis (5*.*5 × 10[−]⁵ rad*/*s) is in close match with the recorded peak rotation of 5 × 10[−]⁵ rad*/*s
- Published in: JGR: Solid Earth (DOI: 10.1029/2020JB020931)

Boundary conditions and the second Amplification of ground motions due to topography

- What will be the effect of 3D Himalayan topography subjected to P, SV and SH waves together??
- It is difficult to incorporate complex topography like the Himalayas in analytical simulation approaches

Past earthquakes in northern India

Boundary conditions

Amplification of ground motions due to topography

- What will be the effect of 3D Himalayan topography subjected to P, SV and SH waves together??
- It is difficult to incorporate complex topography like the Himalayas in analytical simulation approaches
- Therefore, a 3D finite element model is developed of a region in central seismic gap of the Himalayas.

Boundary conditions

Amplification of ground motions due to topography

- What will be the effect of 3D Himalayan topography subjected to P, SV and SH waves together??
- It is difficult to incorporate complex topography like the Himalayas in analytical simulation approaches
- Therefore, a 3D finite element model is developed of a region in central seismic gap of the Himalayas.
- The region under consideration consists of both the Himalayas and the Indo-Ganga basin
- The model incorporates topography and three dimensional material properties for the Himalayas and the Indo-Ganga basin

Boundary conditions Amplification of ground motions due to topography

The developed model is validated with the recorded data for two past earthquakes (Chamoli and Uttarkashi)

Boundary conditions Amplification of ground motions due to topography

- The developed model is validated with the recorded data for two past earthquakes (Chamoli and Uttarkashi)
- Ground motions are simulated for $8.5M_w$ hypothetical earthquake and amplifications are calculated

Boundary conditions Amplification of ground motions due to topography

- The developed model is validated with the recorded data for two past earthquakes (Chamoli and Uttarkashi)
- Ground motions are simulated for $8.5M_w$ hypothetical earthquake and amplifications are calculated
- Amplification is defined as the PGD or PGV obtained at station when topography is considered to the PGD or PGV at the same station when topography is not considered

Boundary conditions and the second state of the second state \blacksquare Amplification of ground motions due to topography

- The developed model is validated with the recorded data for two past earthquakes (Chamoli and Uttarkashi)
- Ground motions are simulated for $8.5M_w$ hypothetical earthquake and amplifications are calculated
- Amplification is defined as the PGD or PGV obtained at station when topography is considered to the PGD or PGV at the same station when topography is not considered
- Amplification observed in the horizontal and vertical direction for
	- **4** Ground displacement

Vertical direction

Boundary conditions and the second Amplification of ground motions due to topography

- The developed model is validated with the recorded data for two past earthquakes (Chamoli and Uttarkashi)
- Ground motions are simulated for $8.5M_w$ hypothetical earthquake and amplifications are calculated
- Amplification is defined as the PGD or PGV obtained at station when topography is considered to the PGD or PGV at the same station when topography is not considered
- Amplification observed in the horizontal and vertical direction for
	- **4** Ground displacement
	- ² Ground velocity
- Regression analysis is carried out to determine the variation of these amplification ratios wrt to elevation.

Published in: AJGS

Quakes just on Earth?? 100 and Ground motion simulations on other planets

Planetary explorations have shown seismic activities on Mars and Moon.

Ground motion recorded on Moon

Quakes just on Earth?? 100 and Ground motion simulations on other planets

- Planetary explorations have shown seismic activities on Mars and Moon.
- In the absence of recorded data. seismic activity is understood by the overturning of boulders when subjected to ground motions

Boulder trails marked on Satellite images (Kumar et al., (2016))

Quakes just on Earth?? 100 and 200 and Ground motion simulations on other planets

- Planetary explorations have shown seismic activities on Mars and Moon.
- In the absence of recorded data. seismic activity is understood by the overturning of boulders when subjected to ground motions
- By static analysis, the minimum PGA required to topple a body is equal to its aspect ratio B*/*H

Boulder trails marked on Satellite images (Kumar et al., (2016))

Quakes just on Earth?? ¹⁰ Ground motion simulations on other planets

- Planetary explorations have shown seismic activities on Mars and Moon.
- In the absence of recorded data. seismic activity is understood by the overturning of boulders when subjected to ground motions
- By static analysis, the minimum PGA required to topple a body is equal to its aspect ratio B/H
- On Mars, high frequency ground motions are simulated using stochastic seismological model to:
	- **4** estimate PGA
	- ² the radius upto which boulder toppling can be encountered

Quakes just on Earth?? 100 and Ground motion simulations on other planets

- Planetary explorations have shown seismic activities on Mars and Moon.
- In the absence of recorded data. seismic activity is understood by the overturning of boulders when subjected to ground motions
- By static analysis, the minimum PGA required to topple a body is equal to its aspect ratio B*/*H
- On Mars, high frequency ground motions are simulated using stochastic seismological model to:
	- **4** estimate PGA
	- ² the radius upto which boulder toppling can be encountered
- However, in dynamic analysis, rocking of a body is governed by:

• Equations

$$
\ddot{\Theta} - \rho^2 \left(1 + \frac{a_Z(t)}{g} \right) (\Theta_C + \Theta) = -\rho^2 \left(\frac{a_X(t)}{g} \right)
$$

$$
\ddot{\Theta} + \rho^2 \left(1 + \frac{a_Z(t)}{g} \right) (\Theta_C - \Theta) = -\rho^2 \left(\frac{a_X(t)}{g} \right)
$$

$$
\Theta_C = \cot^{-1} \frac{H}{g} \text{ and } \rho^2 = \frac{Wg}{I_0}
$$

Quakes just on Earth?? 100 and 200 and Ground motion simulations on other planets

- Planetary explorations have shown seismic activities on Mars and Moon.
- In the absence of recorded data. seismic activity is understood by the overturning of boulders when subjected to ground motions
- By static analysis, the minimum PGA required to topple a body is equal to its aspect ratio B*/*H
- On Mars, high frequency ground motions are simulated using stochastic seismological model to:
	- **4** estimate PGA
	- ² the radius upto which boulder toppling can be encountered
- However, in dynamic analysis, rocking of a body is governed by:

• Equations

$$
\hat{\Theta} - p^2 \left(1 + \frac{a_Z(t)}{g} \right) (\Theta_c + \Theta) = -p^2 \left(\frac{a_X(t)}{g} \right)
$$

$$
\hat{\Theta} + p^2 \left(1 + \frac{a_Z(t)}{g} \right) (\Theta_c - \Theta) = -p^2 \left(\frac{a_X(t)}{g} \right)
$$

$$
\Theta_c = \cot^{-1} \frac{H}{g} \text{ and } p^2 = \frac{Wg}{I_0}
$$

• So, on Moon, ground motions are simulated and dynamic analysis for boulder toppling is carried out

Quakes just on Earth?? 111 and 2012 112 and 20 Ground motion simulations on other planets

• Shortcomings of stochastic seismological model

Quakes just on Earth?? 2012 11:00:00 11:00:00 11:00:00 11:00:00 11:00:00 11:00:00 11:00:00 11:00:00 11:00:00 1 Ground motion simulations on other planets

- Shortcomings of stochastic seismological model
- Therefore, in the next step 3D globe model of Mars (Bozdag et al., (2017)) is used that consists of Globe model of Mars

Quakes just on Earth?? 2012 11:00:00 11:00:00 11:00:00 11:00:00 11:00:00 11:00:00 11:00:00 11:00:00 11:00:00 1 Ground motion simulations on other planets

- Shortcomings of stochastic seismological model
- Therefore, in the next step 3D globe model of Mars (Bozdag et al., (2017)) is used that consists of Globe model of Mars

Quakes just on Earth?? 111 and 2014 112 and 2014 112 and 2014 112 and 2014 12 Ground motion simulations on other planets

- Shortcomings of stochastic seismological model
- Therefore, in the next step 3D globe model of Mars (Bozdag et al., (2017)) is used that consists of Globe model of Mars

- \bullet The developed finite element model incorporates
	- **4** topography
	- ² 3D material properties
	- ³ multiple orbit waves

Quakes just on Earth?? 111 and 2012 112 and 20 Ground motion simulations on other planets

- Shortcomings of stochastic seismological model
- Therefore, in the next step 3D globe model of Mars (Bozdag et al., (2017)) is used that consists of
- The developed finite element model incorporates
	- **4** topography
	- ² 3D material properties
	- ³ multiple orbit waves
- Published in EPSL and GRL

Conclusions 12 Conclusions 12 Conclusions

SEISMIC SOURCE

▶ Extreme value theory provides better estimate to determine regions of SMG

Conclusions **12 September 2018**

SEISMIC SOURCE

▶ Extreme value theory provides better estimate to determine regions of SMG

MEDIUM OF WAVE PROPAGATION

 \triangleright Can we explore reduced micropolar theory further to explore it's applications in the field of seismology?

Conclusions

SEISMIC SOURCE

▶ Extreme value theory provides better estimate to determine regions of SMG

MEDIUM OF WAVE PROPAGATION

 \triangleright Can we explore reduced micropolar theory further to explore it's applications in the field of seismology?

COMPLEX TOPOGRAPHY

 \triangleright Ground displacements and velocities are amplified due to the presence of Himalayan topography. So, it is important to consider the topography of a region to obtain ground motions

Thank you for your attention!

Questions??

Contact:

Anjali Dhabu

Geomatikum, 1329,

University of Hamburg, Germany anjali.dhabu@uni-hamburg.de.com

